

NSCool User's guide

Structure of the Code

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The problem to be solved

The equations to be solved are described in the NSCool_Guide_1 Introduction. They are:

- 1) Structure of the star: the TOV equations.
- 2) Thermal evolution of the star.

How to use the TOV solver is described in NSCool_Guide_3_TOV. Meanwhile, several pre-built stars are available in the directory TOV/Profile.

For the thermal evolution equations, the star is cut at an outer boundary, with radius r_b and density ρ_b (typically $\rho_b = 10^{10}$ gm cm⁻³): at $\rho > \rho_b$ matter is strongly degenerate and thus the structure of the star does not change with time:

The star's structure is calculated before the cooling and not modified thereafter. (Almost: NSCool allows for small density changes in the outer part of the star, if required)

Only the energy balance and transport equations are solved as a function of time:

- two first order partial differential equations to get L(r,t) and T(r,t) with
- an initial L and T profile: L(r,t=0) and T(r,t=0)
- two boundary conditions, at r=0 and $r=r_b$.

Note: the heat transport is a diffusion equation and numerically unstable if treated improperly. Numerical stability is achieved using an implicit scheme ("Henyey scheme") similar to the textbook Crank-Nicholson.

Rewriting the thermal evolution equations

The equations to solve:

Unam

Energy balance

$$\frac{d(Le^{2\Phi})}{dr} = -\frac{4\pi r^2 e^{\Phi}}{\sqrt{1 - 2Gm/c^2r}} \left(C_v \frac{dT}{dt} + e^{\Phi}(Q_v - Q_h) \right) \qquad \frac{d(Te^{\Phi})}{dr} = -\frac{1}{\lambda} \cdot \frac{Le^{\Phi}}{4\pi r^2 \sqrt{1 - 2Gm/c^2r}}$$

Use red-shifted functions: $\mathcal{T} \equiv e^{\Phi} \mathcal{T}$ and $\mathcal{L} \equiv e^{2\Phi} \mathcal{L}$

and the Lagrangian coordinate a (baryon number)

 $da = 4\pi r^2 dI n_B = \frac{4\pi r^2 n_B dr}{\sqrt{1 - 2Gm/c^2 r}}$

to get:

$$\frac{d\mathcal{L}}{da} = -\frac{C_v}{n_B}\frac{d\mathcal{T}}{dt} - e^{2\Phi}\frac{Q_v - Q_h}{n_B} \quad \text{or} \quad \frac{d\mathcal{T}}{dt} = -e^{2\Phi}\frac{Q_v - Q_h}{C_v} - \frac{n_B}{C_v}\frac{d\mathcal{L}}{da}$$

and:

$$\frac{d\mathcal{T}}{da} = -\frac{1}{\lambda} \frac{\mathcal{L}}{(4\pi r^2)^2 n_B e^{\Phi}} \quad \text{or} \quad \mathcal{L} = -\lambda \ (4\pi r^2)^2 n_B e^{\Phi} \frac{d\mathcal{T}}{da}$$

which we write as:

$$\frac{d\mathcal{T}}{dt} = F\left(\mathcal{T}, \frac{d\mathcal{L}}{da}\right) \quad \text{and} \quad \mathcal{L} = G\left(\mathcal{T}, \frac{d\mathcal{T}}{da}\right)$$

(the \mathcal{T} dependence of *F* and *G* comes from Q_v , Q_h , C_v , and λ)

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Finite differencing the equations

For finite differencing these equations one divides the star into shells, at radii $r_0=0, r_1, ..., r_i, ..., r_{imax}$. *L*, being a flux, is defined at the shell interfaces while T is understood as the average in the interior of each shell: it is common to write then L_i and $T_{i+\frac{1}{2}}$ to emphasize this.

Since fortran does not like loop indices with half integer values I used:

f is defined at *i* = 0, 2, 4, ..., *i*_{max}-1

 \mathcal{T} is defined at *i* = 1, 3, 5, ..., *i*_{max}



$$\frac{d\mathcal{T}}{dt} = F\left(\mathcal{T}, \frac{d\mathcal{L}}{da}\right) \longrightarrow \frac{d\mathcal{T}_{i}}{dt} = F\left(\mathcal{T}_{i}, \frac{d\mathcal{L}}{da}\Big|_{i}\right) \text{ with } \frac{d\mathcal{L}}{da}\Big|_{i} = \frac{\mathcal{L}_{i+1} - \mathcal{L}_{i-1}}{da_{i-1} + da_{i}}$$
for $i = 1, 3, 5, ...$

$$\mathcal{L} = G\left(\mathcal{T}, \frac{d\mathcal{T}}{da}\right) \longrightarrow \mathcal{L}_{i} = G\left(\mathcal{T}|_{i}, \frac{d\mathcal{T}}{da}\Big|_{i}\right) \quad \text{with} \quad \mathcal{T}|_{i} = \frac{\mathcal{T}_{i+1} + \mathcal{T}_{i-1}}{2} \text{ and } \left|\frac{d\mathcal{T}}{da}\Big|_{i} = \frac{\mathcal{T}_{i+1} - \mathcal{T}_{i-1}}{da_{i-1} + da_{i}}$$

for *i* = 2, 4, 6, ...

where da_i is the number of baryons between r_{i-1} and r_i

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Stepping forward in time

Assuming we know the profiles of \mathcal{T} and \mathcal{L} at time t: \mathcal{T}^{old} and \mathcal{L}^{old} we can write for \mathcal{T} and \mathcal{L} at time t'=t+dt:

Explicit scheme

$$\frac{d\mathcal{T}}{dt} = F\left(\mathcal{T}, \frac{d\mathcal{L}}{da}\right) \longrightarrow \mathcal{T} = \mathcal{T}^{\text{old}} + dt \cdot F\left(\mathcal{T}^{\text{old}}, \frac{d\mathcal{L}^{\text{old}}}{da}\right)$$
$$\mathcal{L} = G\left(\mathcal{T}, \frac{d\mathcal{T}}{da}\right) \longrightarrow \mathcal{L} = G\left(\mathcal{T}^{\text{old}}, \frac{d\mathcal{T}^{\text{old}}}{da}\right)$$

this is very easy to integrate BUT:

it is numerically unstable unless dt is very small (Courant dixit)

Better: evaluate *F* and *G* at the new values of \mathcal{T} and \mathcal{L} :

 $\frac{d\mathcal{T}}{dt} = F\left(\mathcal{T}, \frac{d\mathcal{L}}{da}\right) \longrightarrow \mathcal{T} = \mathcal{T}^{\text{old}} + dt \cdot F\left(\mathcal{T}, \frac{d\mathcal{L}}{da}\right)$ $\mathcal{L} = G\left(\mathcal{T}, \frac{d\mathcal{T}}{da}\right) \longrightarrow \mathcal{L} = G\left(\mathcal{T}, \frac{d\mathcal{T}}{da}\right)$

Implicit scheme

> this is numerically stable (and allows large *dt*) BUT: extracting the new \mathcal{T} and \mathcal{L} is tough (particularly \mathcal{T} because it is inside Q_v , Q_h , C_v , and λ)

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Solving the implicit equations by iterations

Assuming we know the profiles of \mathcal{T} and \mathcal{L} at time t: \mathcal{T}^{old} and \mathcal{L}^{old} we can find the new \mathcal{T} and \mathcal{L} at time t'=t+dt by successive approximations $(\mathcal{T}^{(0)}, \mathcal{L}^{(0)}) \rightarrow (\mathcal{T}^{(1)}, \mathcal{L}^{(1)}) \rightarrow (\mathcal{T}^{(2)}, \mathcal{L}^{(2)}) \rightarrow (\mathcal{T}^{(3)}, \mathcal{L}^{(3)}) \rightarrow \dots$

As an initial guess for $(\mathcal{T}^{(0)}, \mathcal{L}^{(0)})$ one can take $(\mathcal{T}^{(0)}, \mathcal{L}^{(0)}) = (\mathcal{T}^{old}, \mathcal{L}^{old})$ or extrapolate from $(\mathcal{T}^{old}, \mathcal{L}^{old})$ and the previous values $(\mathcal{T}^{older}, \mathcal{L}^{older})$.

Evaluate the functions F and G with $\mathcal{T}_{i}^{(k)}$ and $\mathcal{L}_{i}^{(k)}$ to obtain $\mathcal{T}_{i}^{(k+1)}$ and $\mathcal{L}_{i}^{(k+1)}$:

$$\mathcal{T}_{i}^{(k+1)} = \mathcal{T}_{i}^{\text{old}} + dt \cdot F\left(\mathcal{T}_{i}^{(k)}, \frac{d\mathcal{L}}{da}\Big|_{i}^{(k)}\right) \qquad \mathcal{L}_{i}^{(k+1)} = G\left(\mathcal{T}_{i}^{(k)}, \frac{d\mathcal{T}}{da}\Big|_{i}^{(k)}\right)$$

then plug back $\mathcal{T}_{i}^{(k+1)}$ and $\mathcal{L}_{i}^{(k+1)}$ into F and G to obtain $\mathcal{T}_{i}^{(k+2)}$ and $\mathcal{L}_{i}^{(k+2)}$ and so on until some K when $\mathcal{T}_{i}^{(K+1)} \cong \mathcal{T}_{i}^{(K)}$ and $\mathcal{L}_{i}^{(K+1)} \cong \mathcal{L}_{i}^{(K)}$ (All $\mathcal{T}_{i}^{(K)}$ and $\mathcal{L}_{i}^{(K)}$ are successive approximations *at the same time t'*. \mathcal{T}_{i}^{old} does not change, it is at time t !)

 1^{2} and 2^{1} and 2^{1} are successive approximations at the same time t. 2^{1} does not change, it is at time t.)

As long as the initial guess ($\mathcal{T}^{(0)}$, $\mathcal{L}^{(0)}$) is not too far from the solution the method will converge to the solution (maybe in 10 iterations ?)

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Improvement: the Henyey scheme

Instead of using brute force iterations, the Henyey scheme use the Newton-Raphson method for solving multi-dimensional equations.

Write the equations as: $\begin{cases} \mathcal{T} - \mathcal{T}^{\text{old}} - dt \cdot F\left(\mathcal{T}, \frac{d\mathcal{L}}{da}\right) = 0\\ \mathcal{L} - G\left(\mathcal{T}, \frac{d\mathcal{T}}{da}\right) = 0 \end{cases}$

or, in N dimensional notation:

$$\Phi(X) = 0 \quad \text{with} \quad X = \begin{pmatrix} \mathcal{L}_0 \\ \mathcal{T}_1 \\ \mathcal{L}_2 \\ \mathcal{T}_3 \\ \vdots \end{pmatrix} \quad \text{and} \quad \Phi(X) = \begin{pmatrix} \Phi_0(X) \\ \Phi_1(X) \\ \Phi_2(X) \\ \Phi_3(X) \\ \vdots \end{pmatrix} \quad f(x_{k+1}) = 0 \quad \leftrightarrow \\ f(x_k) + f'(x_k) \cdot (x_{k+1} - x_k) = 0 \\ \Rightarrow x_{k+1} = x_k - [f'(x_k)]^{-1} \cdot f(x_k)$$

and the Newton-Raphson iteration procedure is: $X^{(k+1)} = X^{(k)} - [D\Phi(X^{(k)})]^{-1} \cdot \Phi(X^{(k)})$ where $[D\Phi(X)]$ is the NxN derivative matrix of $\Phi(X)$ and $[D\Phi(X)]^{-1}$ the inverse matrix.

This involves calculating T derivatives of Q_V , Q_h , C_V , and λ and inverting a large matrix. Fortunately this matrix is tri-diagonal and its inversion is straightforward !

One still have to preform iterations but the convergence can be much faster than brute force.

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The Newton method

to solve f(x)=0



Checking for iteration convergence and time step control

The Newton-Raphson iterations go as:

 $\begin{aligned} \mathcal{T}_{i}^{(k)} &\to \mathcal{T}_{i}^{(k+1)} = \mathcal{T}_{i}^{(k)} + \delta \mathcal{T}_{i}^{(k)} & \text{[i=1, 3, 5, ...]} \\ \mathcal{L}_{i}^{(k)} &\to \mathcal{L}_{i}^{(k+1)} = \mathcal{L}_{i}^{(k)} + \delta \mathcal{L}_{i}^{(k)} & \text{[i=0, 2, 4, ...]} \end{aligned}$

Convergence will be considered to have been achieved when

$$\operatorname{Max}_{i=1,3,5,\ldots}\left(\frac{\delta \mathcal{T}_{i}^{(k)}}{\mathcal{T}_{i}^{(k)}}\right) < \epsilon_{T} \quad \text{and} \quad \operatorname{Max}_{i=0,2,4,\ldots}\left(\frac{\delta \mathcal{L}_{i}^{(k)}}{\mathcal{L}_{i}^{(k)}}\right) < \epsilon_{L}$$

Values of ε_T and ε_L of the order of 10⁻¹⁰ can be reached in 4 - 6 iterations.

However, if $\mathcal{T}_i^{(0)}$ and/or $\mathcal{L}_i^{(0)}$ are too far away from the solution, iterations go on forever:

the loop is exited, the time step *dt* is shortened and the iteration procedure restarted.

(It is not unusual to see *dt* being cut many times, e.g., when a phase transition (superfluidity/superconductivity) occurs at some point in the star. Sometimes things go real bad (dt → almost zero): "Ctrl-C" is the only solution, and figure out what's happening.)

Time step control: at every new time step *dt* is increased: $dt \rightarrow dt (1+\alpha)$ ($\alpha \sim 0.2$) but:

- if Newton-Raphson converged in << 5 steps a larger α is chosen
- if Newton-Raphson needed > 10 steps to converge a smaller α is chosen
- if \mathcal{T} and/or \mathcal{L} changed too much (from \mathcal{T}^{old} and/or \mathcal{L}^{old}) a smaller α is chosen,

while if they changed ways too much, the time step is recalculated with a smaller dt.



The boundary conditions

Inner boundary condition: L(r=0) = 0 or $\mathcal{L}_{i=0} = 0$

This is easily implemented by initially starting with $\mathcal{L}_{i=0}^{(k=0)} = 0$ and imposing $\delta \mathcal{L}_{i=0}^{(k)} = 0$ at every iteration.

Outer boundary condition (see NSCool_Guide_1_Introduction):

It is (at $r = r_b$): $L(r_b) = 4\pi R^2 \sigma_{SB} [T_e(T_b)]^4$ with $T_b \equiv T(r_b)$

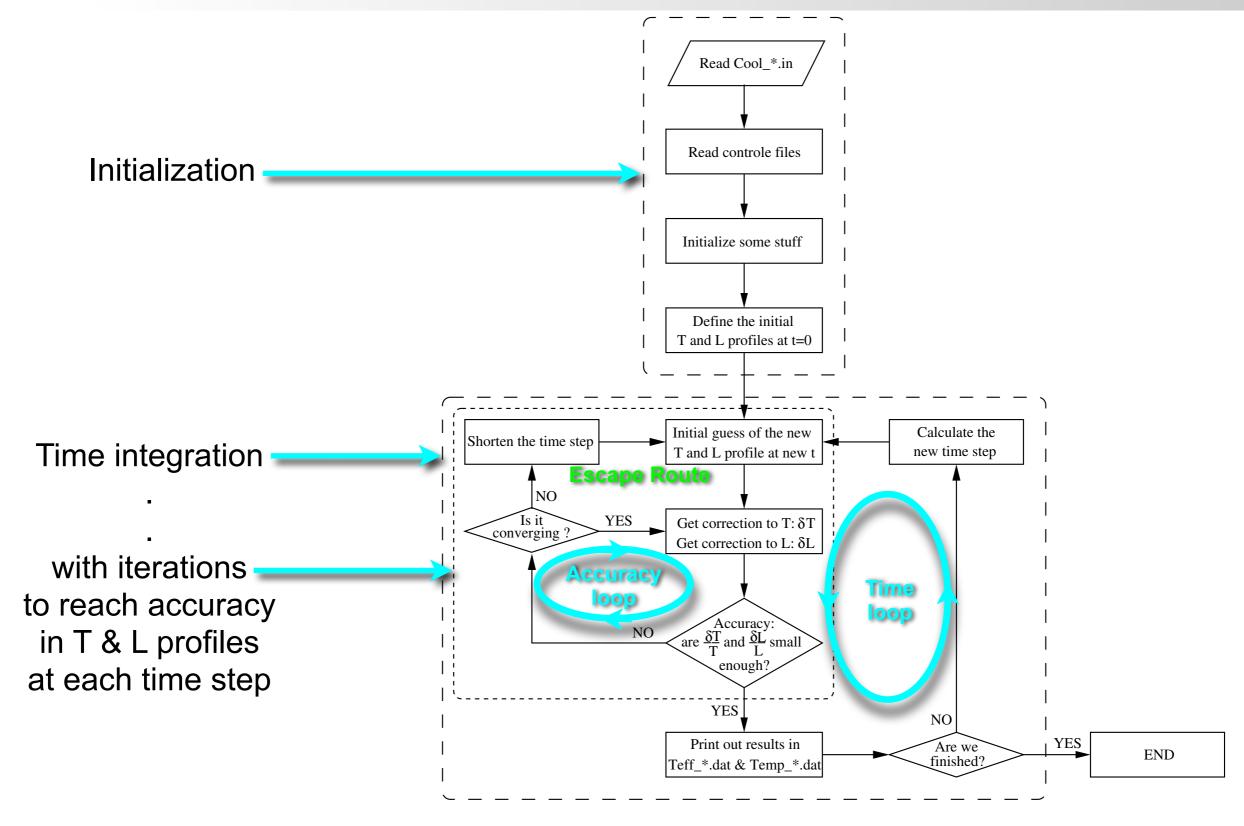
where (in present notations): $L(r_b) = e^{-2\Phi(i_{max}-1)} \mathcal{L}(i_{max}-1)$ and $T(r_b) = e^{-\Phi(i_{max})} \mathcal{T}(i_{max})$ and $T_e(T_b)$ is a function (a "T_e-T_b" relationship) obtained from some envelope model.

This is implemented as part of the inversion of the matrix $[D\Phi(X)]$

Add more details about this !

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Flow diagram of NSCool



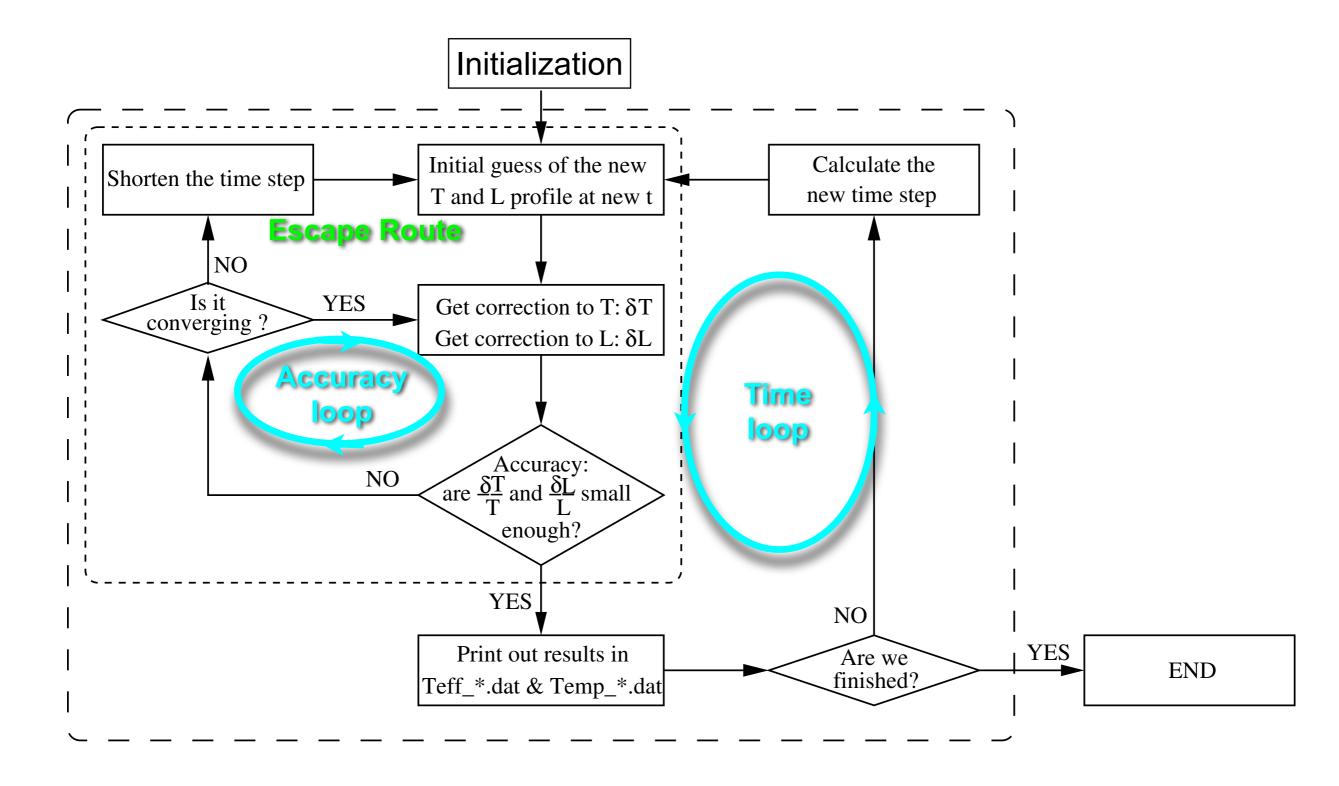
Notice: NSCool contains an extra "model loop" to run several cooling models from the same Cool_*.in file.

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Flow diagram of NSCool (bigger)



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Code Structure



Reading the NSCool.f file

The next slides describe the structure of NSCool.f :

Implementation of the previous flow diagram

There are many sections of just screen print out (unimportant for now). They are all marked the same way between two line of:

Lines like these would include commands for magnetic field evolutions (not used anymore).

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00	NSCool.f	
end if		6
end if	<pre>_rate(time+dtime,dtime,m_dot)</pre>	
	_velocity(m_dot)	
if (pscreen.ge if (pscreen.	.2) then eq.3) read(5,*)	
read(5,*)	cq. 5) + cuu(5, 5)	
<pre>write(6,*)</pre>		
	1a50)	.=
print '(2a10,	li5,1a53)','********','step#=',istep, *********	
±	1050)','*********************************	
1 '*********	******	
	,1p1e10.3),a30,0p1f6.3)' ,	
1	<pre>'time =',(time+dtime)/year,</pre>	
2 3 'dtime	'dtime =',dtime/year, /odtime =',dtime/odtime	<u>o</u> =
print *	volutione - , actile/ vactile	<u> </u>
if (chtemp.eq	.1.) then	
	<pre>0p1f5.2,a9,1p1e9.2,a3,1p1e9.2)',</pre>	
	limited by TEMP change, mdtemp =',mdtemp,	
2 'atrh end if	o=',rrho(icht),'T=',temp(icht)	
if (chstoke.e	q.1.) then	
	<pre>0p1f5.2,a9,1p1e9.2,a3,1p1e9.2)',</pre>	- II - 2 - 2
	<pre>limited by STOKE change, mdstoke =',mdstoke,</pre>	
2 'atrh end if	<pre>0=',rrho(ichs),'S=',stoke(ichs)</pre>	
if (chtrial.e	g.1) then	
print '(a40)	,	
	ime limited by ITRIAL'	
end if end if		
		📗 📛 🛫
		(L) (D)
***** Calculate nt	emp & nlum for first guess ***********************************	*** 🛛 🚄 놀
	.) print *,iGuessing NLum & NTempi	¥ 📜 📒
coeff_int=0.8d		- T T 🕚
** NSCool.f 35%	(490,13) (Fortran)	
0.0		
00	NSCool.f	
BBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBB		
INCLUDE 'Bfield BBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBB	/Bfield_3.inc.f'	
		÷ 🕘 😫
NSCool.f 38% (4	76,22) (Fortran)	
		A manufacture of the second

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Essential variables in NSCool.f

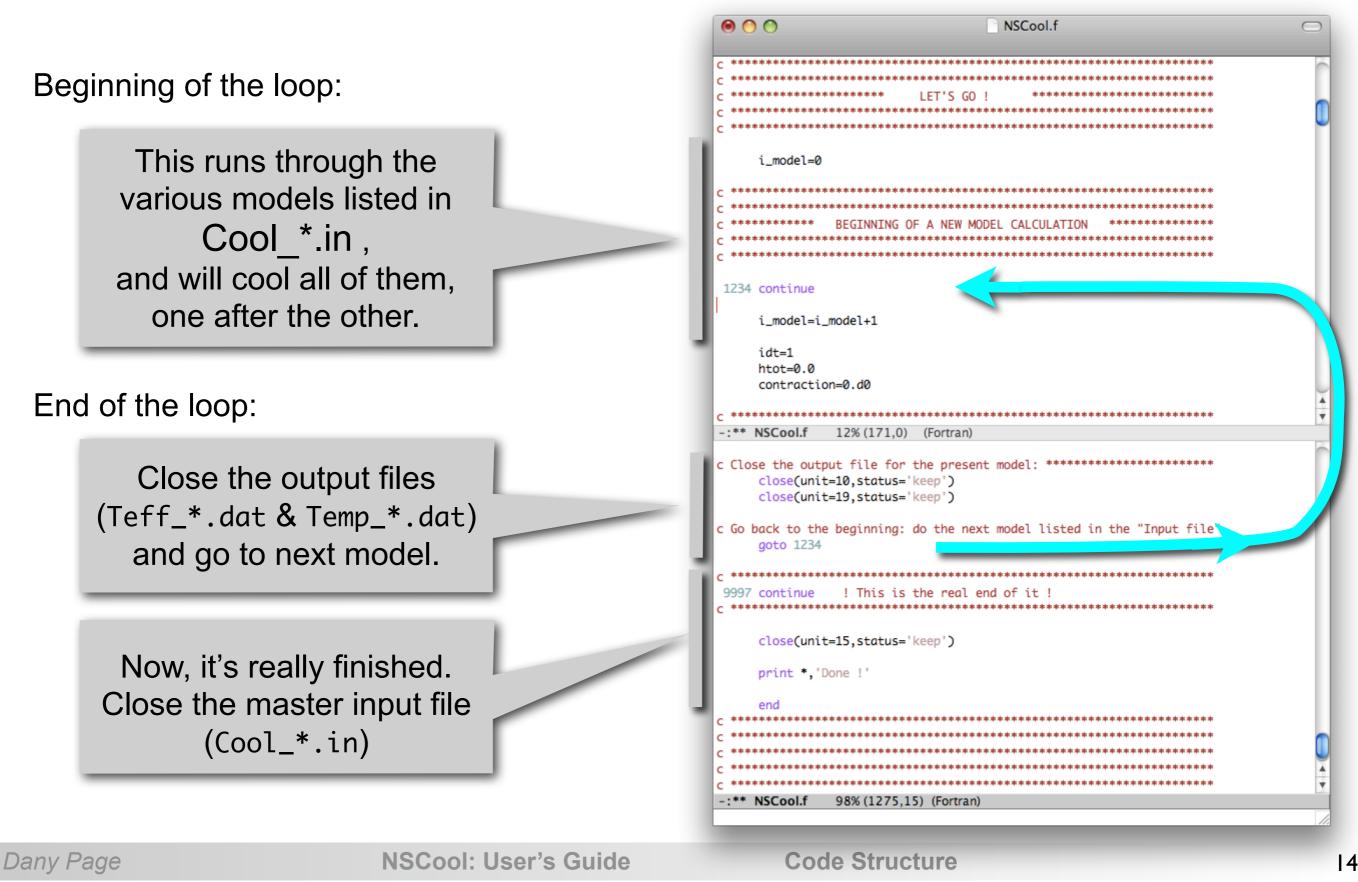
Code variable		Code variable		The
time dtime temp(i) ntemp(i)	t dt \mathcal{T}_i^{old} $\mathcal{T}_i^{(k)}$	istep itrial	time index iteration index	t but var
dtemp(i) delt(i) lum(i) nlum(i) dlum(i) dell(i)	$d\mathcal{T}_{i}^{(k)}/da$ $\delta\mathcal{T}_{i}^{(k)}$ \mathcal{L}_{i}^{old} $\mathcal{L}_{i}^{(k)}$ $d\mathcal{L}_{i}^{(k)}/da$ $\delta\mathcal{L}_{i}^{(k)}$	Code variable rad(i) rrho(i) debar(i)	r ρ da	

The new time is t'=t+dt but there is no variable for t'

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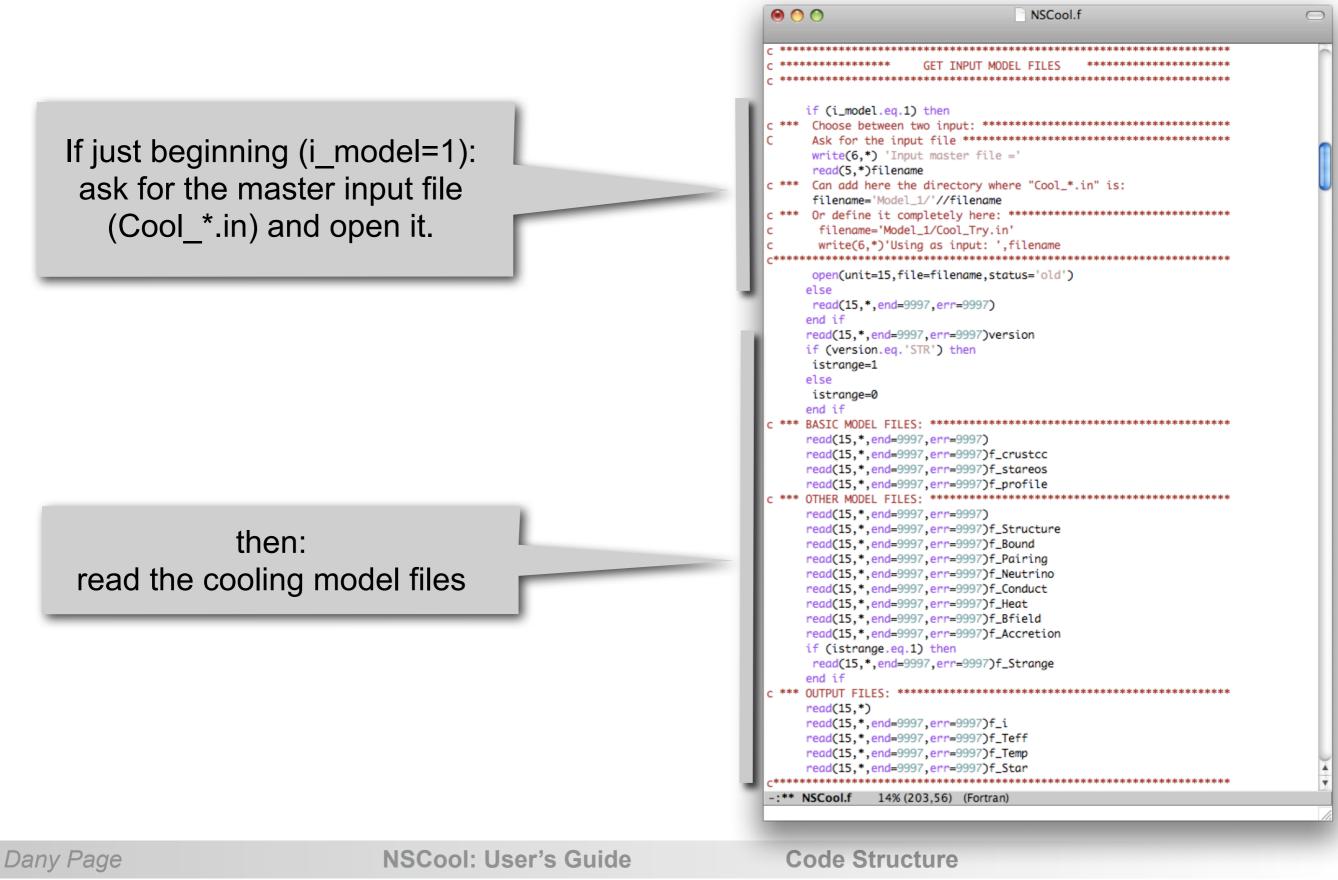


The "model" loop





The "Input File" (Cool_*.in)

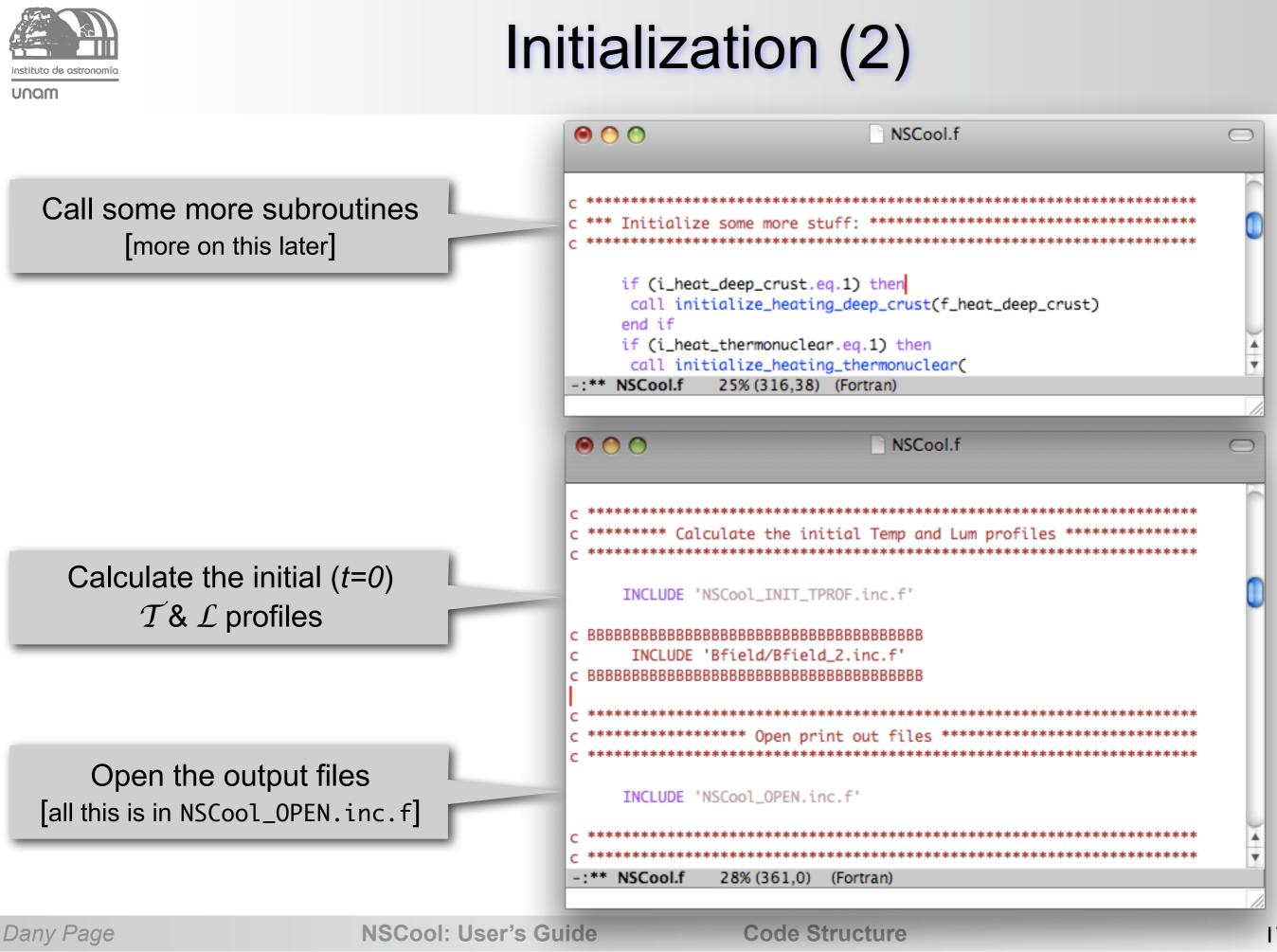




Initialization (1)

	00	NSCool.f	\bigcirc
Open and read the model files (the ones listed in Cool_*.in) [all this is in NSCool_READ.inc.f]	•	<pre>READ THE ABOVE FILES ************************************</pre>	
[more on this later]	*** Get the time i ************************************	ndependent pieces of physics: ************************************	•
	00	NSCool.f	0
physics (as, e.g., the e [¢] 's,)	if (debug.ge.1	<pre>e T-independent coefficients ************************************</pre>	

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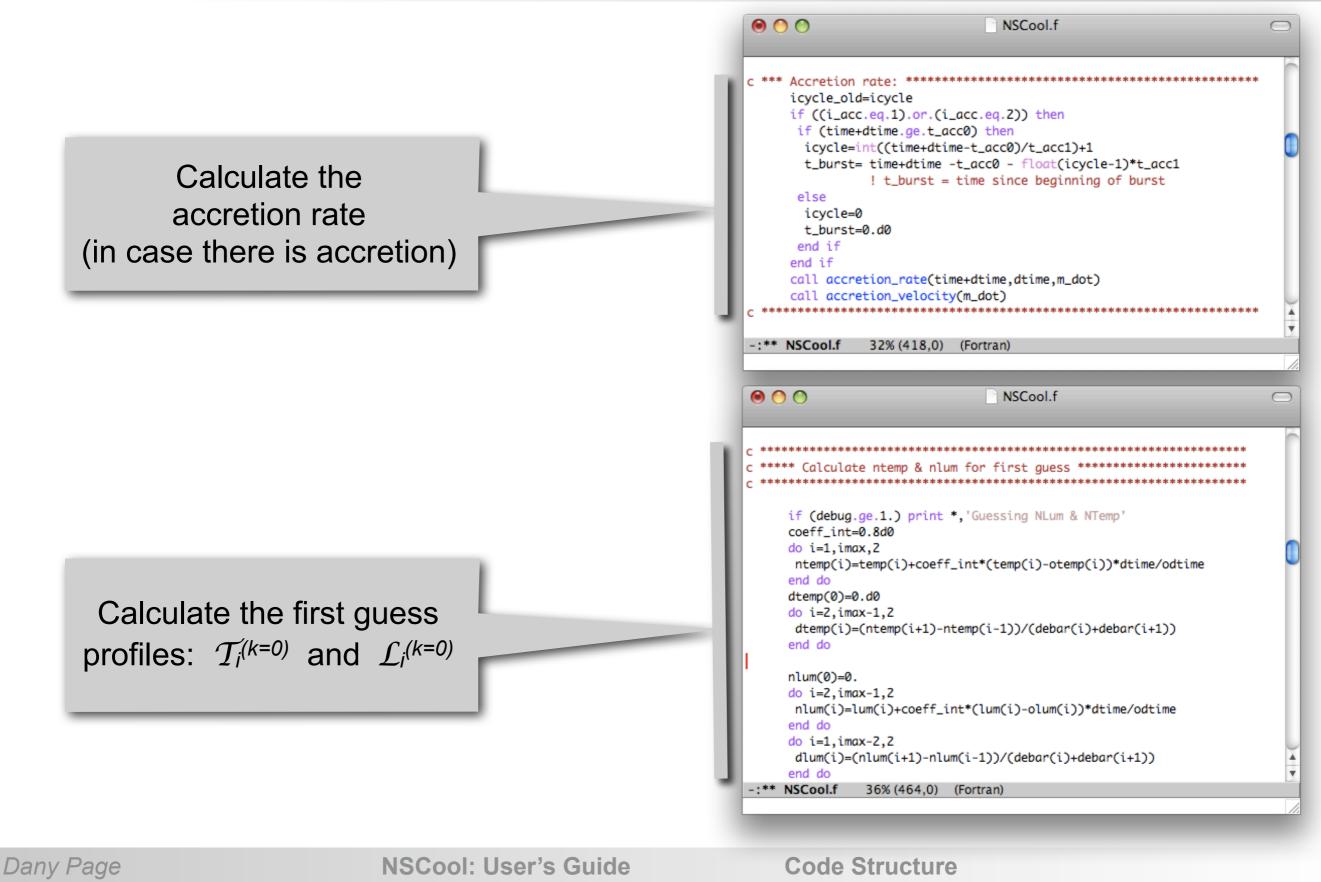
The "time loop"

Beginning of the loop:	00	NSCool.f	
The time stepping loop (after some little set-up, as resetting the time !)	C ************ C ************ C ********	**************************************	
	c ************** time=tim icycle=0 c **********		
End of the loop:	c **************** c itprint itprint= c **********		

<pre>if (time/year.ge.timemax) goto 9998 if ((sign_l*teffective).lt.tempmin) goto 9998</pre>	-:** NSCool.f	29% (386,0) Fortran)	▼ //.
c ************************************			
c ************************************		It stops when you run	
c Close the output file for the present model: ************************************	*****	out of time steps or you run out of time	
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Prepare for iterations





The Newton-Raphson loop

Reset the iteration loop counter: (this is also a branch point in case of failure)

Beginning of the iteration loop:

Increment the iteration counter

Too many iterations: it is not converging (start again with a smaller time step dt)

End of the iteration loop:

Escape Route:

First Exit

- Converged: go to next time step.
- Not converged: go to next iteration.

0 0 NSCool.f THIS IS THE MAIN TIME LOOP do 9999 istep=1.istepmax debug=0. if (istep.ge.istep_debug) debug=debug_keep if (debug.ge.1.) print *, 'Going: istep=', istep 2345 itrial=0 Branch back here in case: - Too many iteration in Newton-Raphson Envelope boundary condition cannot be solved Temp has changed too much NSCool.f **** Branch here if new trial ****** itrial=itrial+1 ! This is the Newton-Raphson loop if (itrial.eq.itrial_max+1)then tcut=dsqrt(dt0) if (time.le.1.e5) tcut=dsqrt(dt1) dtime=dtime/tcut goto 2345 end if -:** NSCool.f 39% (498,0) (Fortran) ******* Decide if converged or not: if ((ratiot.lt.mratt).and.(ratiol.lt.mratl).and.(ratios.lt.mrats)) x then ! Converged ! continue to next time step continue else ! Not converged ! Go back for another iteration aoto 2000 end if :** NSCool.f 66% (855.0) (Fortran)

Code Structure

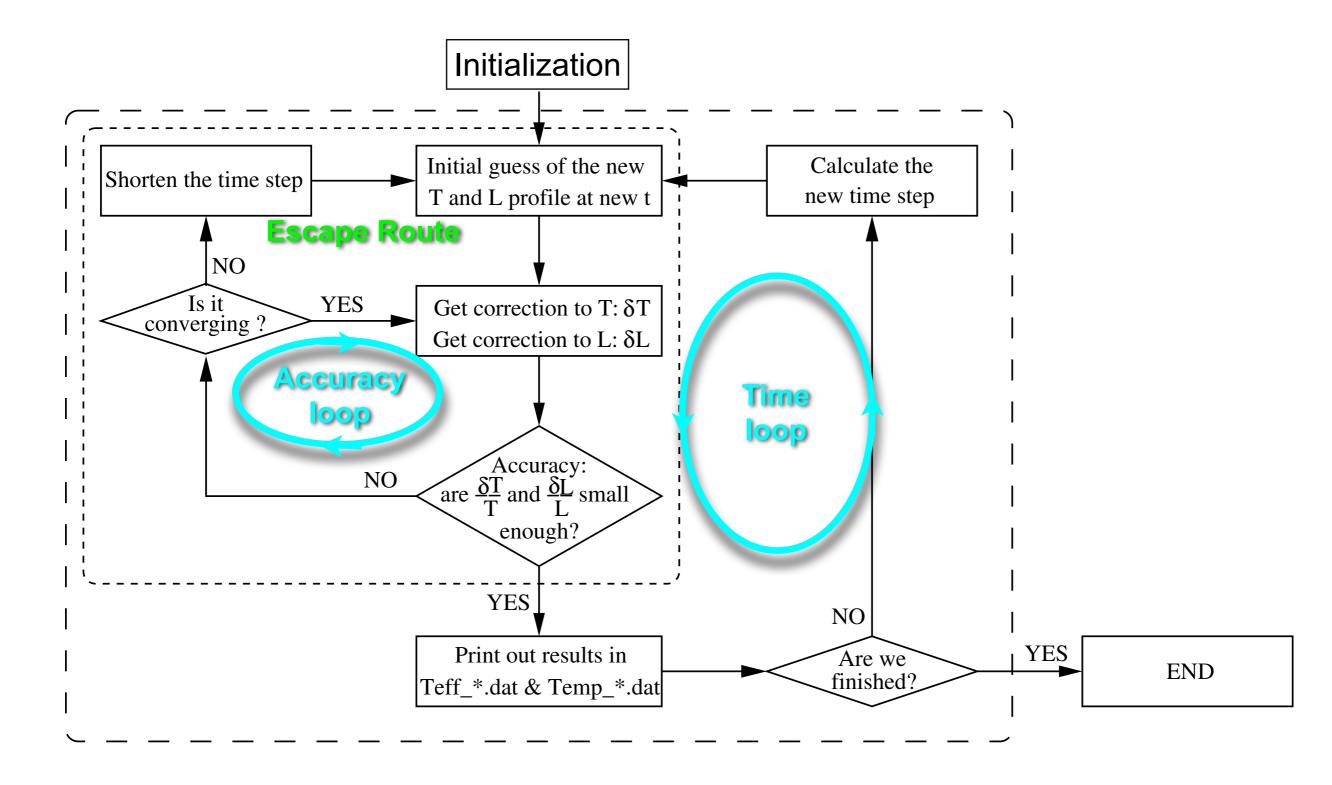
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Flow diagram of NSCool (bigger)



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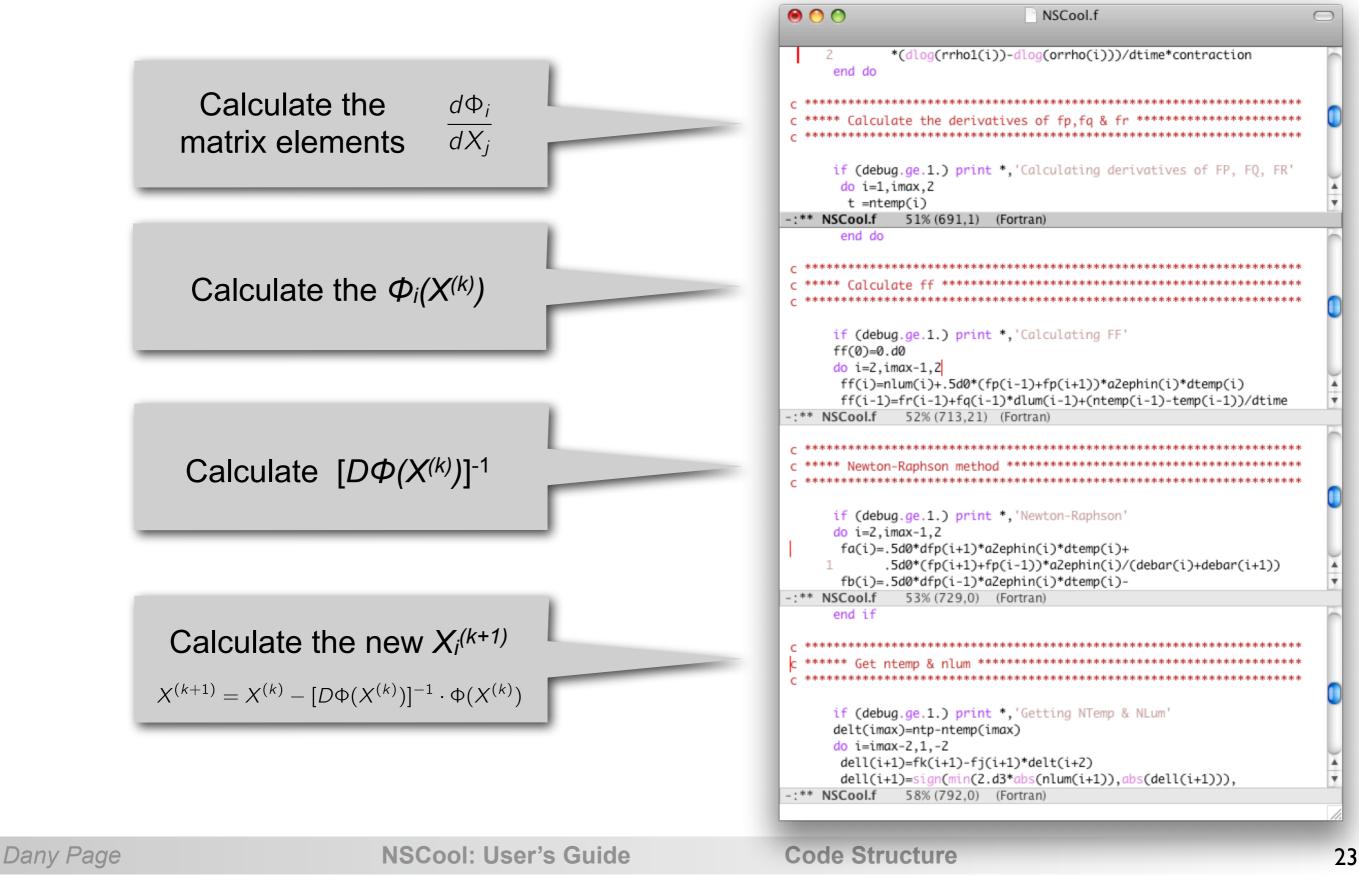


Prepare matrix $[D\Phi(X^{(k)})]$

			00	NSCool.f	\bigcirc
	Adjust density in outer part, if required.			**************************************	0
			do i=imax-1,ie		× •
			-:** NSCool.f 41%	6 (518,0) (Fortran)	6
	Calculates physics			**************************************	
	$(Q_v, Q_h, C_v, \text{ and } \lambda)$ at $T_i^{(k)}$		<pre>do i=1,imax,2 t=ntemp(i)/ep d=rrho(i)</pre>	.) print *,'Calculating physics at NTemp' hi(i)	
T ;(k) i	s changed to $(1-\varepsilon) \cdot T_i^{(k)}$		<pre>a=a_cell(i) a1=a_ion(i) z=z_ion(i) call peutrino</pre>	(i,t,d,a,z,qnu(i),	<u> </u>
	• • • •			6 (544,0) (Fortran)	
	alculate the derivatives			**************************************	
	Readjust density in outer part, if required.		<pre>tinc=max(1.d-1 do i=1,imax,2</pre>	.) print *,'Calculating density at NTemp''' 2,ratiot/1.d1) mp(i)*(1.d0-tinc)	
			do i=imax-1,ie	nv+1,-2 6 (590,0) (Fortran)	Å
	Recalculates physics		c ***** Calculate th	**************************************	
	$(Q_{\nu}, Q_{h}, C_{\nu}, \text{ and } \lambda)$ at $(1-\varepsilon) \cdot T_{i}^{(k)}$		<pre>if (debug.ge.1 do i=1,imax,2 t=ntemp1(i)/e d=rrho1(i)</pre>	.) print *,'Calculating physics at NTemp''' phi(i)	
			•••	6 (623,0) (Fortran)	
		la Quida	Codo Cárra	- chung	
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Calculate $[D\Phi(X^{(k)})]$, invert it and get $X^{(k+1)}$



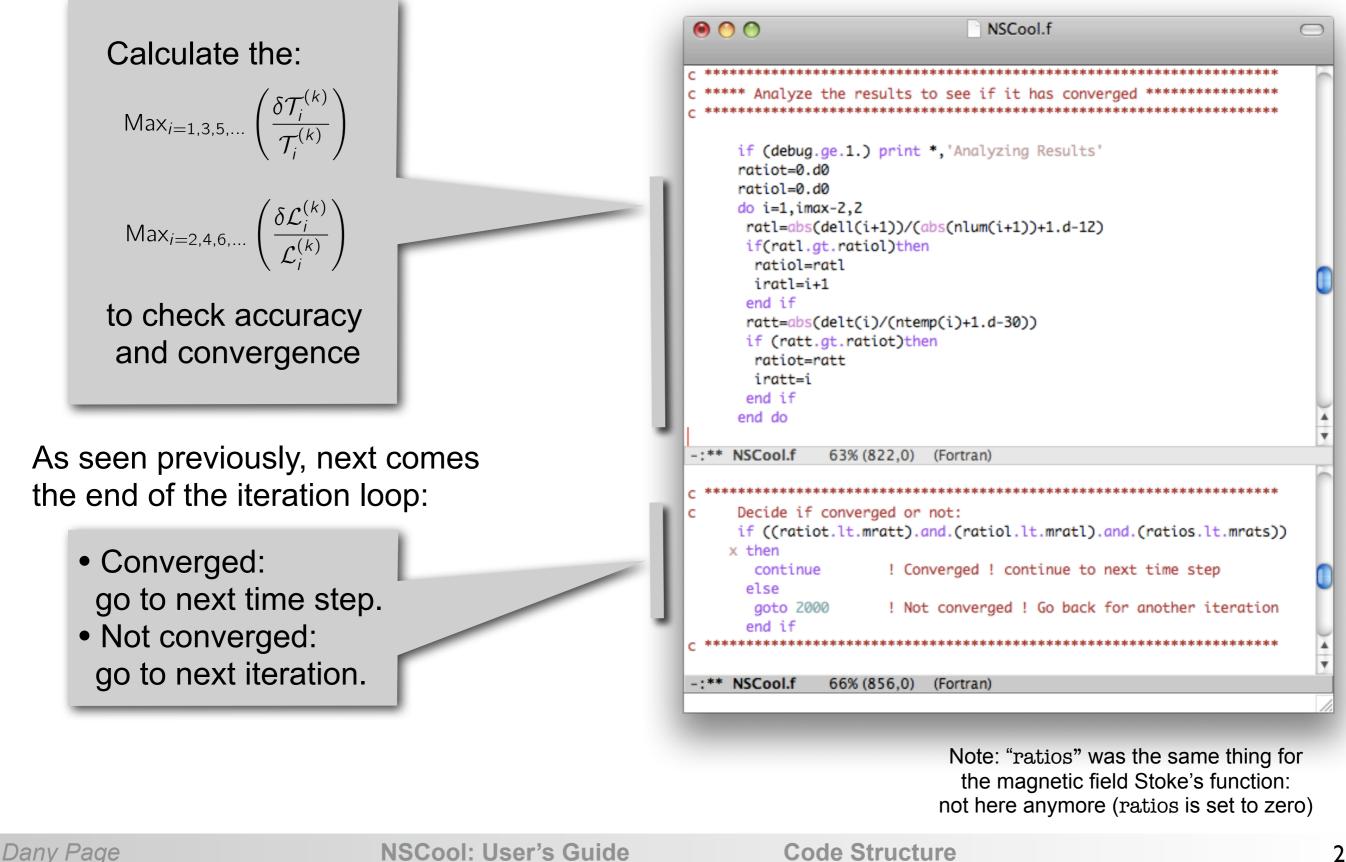


The outer boundary condition

This solves the condition $\mathcal{L}(r_b) = 4\pi R^2 \sigma_{SB} [T_e(T_b)$ using Newton's method The function fteff() i	b)] ⁴ with $T_b \equiv T(r_b)$	<pre>if (ifteff.ne.15 epsilon=1.d-8 precision=1.d-1 coeff=4.d0*pi*r lhs=nlum(imax-1 ntp=ntemp(imax) tp0_keep=ntp teff0=fteff(tp0 1 tim 2 deb if(debug.eq50 tp1=(1.d0+epsil teff1=fteff(tp1 1 tim 2 deb if(debug.eq50 derivative=coef derivative=coef derivative=-fj(if(debug.eq50 function=lhs-fj if(debug.eq50 ntp=tp0-functio if(debug.eq50 if(de</pre>	<pre>print *,'Boundary Condition' b) then 2 radius**2*5.67d-5*e2phi(imax)/lsol b)+fk(imax-1)+fj(imax-1)*ntemp(imax) b) /ephi(imax),ifteff,eta,bf_r(imax),istep, ne,ts1,ts2,z_ion(imax),a_ion(imax),rrho(imax), nug) b) print *,'Tb0, Te0 =',tp0,teff0 on)*tp0 //ephi(imax),ifteff,eta,bf_r(imax),istep, ne,ts1,ts2,z_ion(imax),a_ion(imax),rrho(imax), nug) b) print *,'Tb1, Te1 =',tp1,teff1 ff*(teff1**4-teff0**4)/(epsilon*tp0) fimax-1)-derivative (imax-1)-derivative =',derivative (imax-1)*tp0-coeff*teff0**4 b) print *,'Punction =',function m/derivative b) print *,'Del(Tp)/Tp =',abs(tp0-ntp)/tp0 b) print *,'> New Tb =',ntp b.or.(ntp.gt.1.e12)) then ! In case the method diver</pre>		
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Check accuracy



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Getting the new dt

Now that iterations have converged, NSCool analyzes the process and prepares for the next time step.

NSCool tries to increase the time step dt (=dtime variable) as: dtime \rightarrow scale_dt*dtime

Factors controlling scale_dt:

SCool.f	\Box
c ******** PREPARATION TO CALCULATE THE NEW TIME STEP ************************************	k# 6
C ************************************	k ak
<pre>c This is a delicate part, based on experience and many trials and err c It works pretty well, so avoid changing it ! c</pre>	rors.
c PHILOSOPHY OF TIME STEP CONTROL: c	
<pre>c (Time of step just finished is "time+dtime", not just time !) c The new "dtime" will be "scale_dt*dtime" with "scale_dt" calculated c Allows for 2 different "scale_dt": at early time, while relaxing fro c conditions, accuracy is not important and one can allow for larger t c "scale_dt0" and "scale_dt1" are read from the file</pre>	om initial
<pre>c NUM_PARAM.dat in NSCool_READ.inc.f c and are the maximum allowed relative increase in "dtime"</pre>	▲
C ************************************	**
	1

1) If \mathcal{T}_i differs too much from \mathcal{T}_i^{old} , scale_dt is shortened. This uses

max_dtemp = Max_{i=1,3,5,...}
$$\left(\frac{|\mathcal{T}_i - \mathcal{T}_i^{\text{old}}|}{\mathcal{T}_i^{\text{old}}}\right)$$

2) If the resulting scale_dt is too small, i.e., \mathcal{T}_i differs way too much from $\mathcal{T}_i^{\text{old}}$, the time step is recalculated with a shorted dtime.



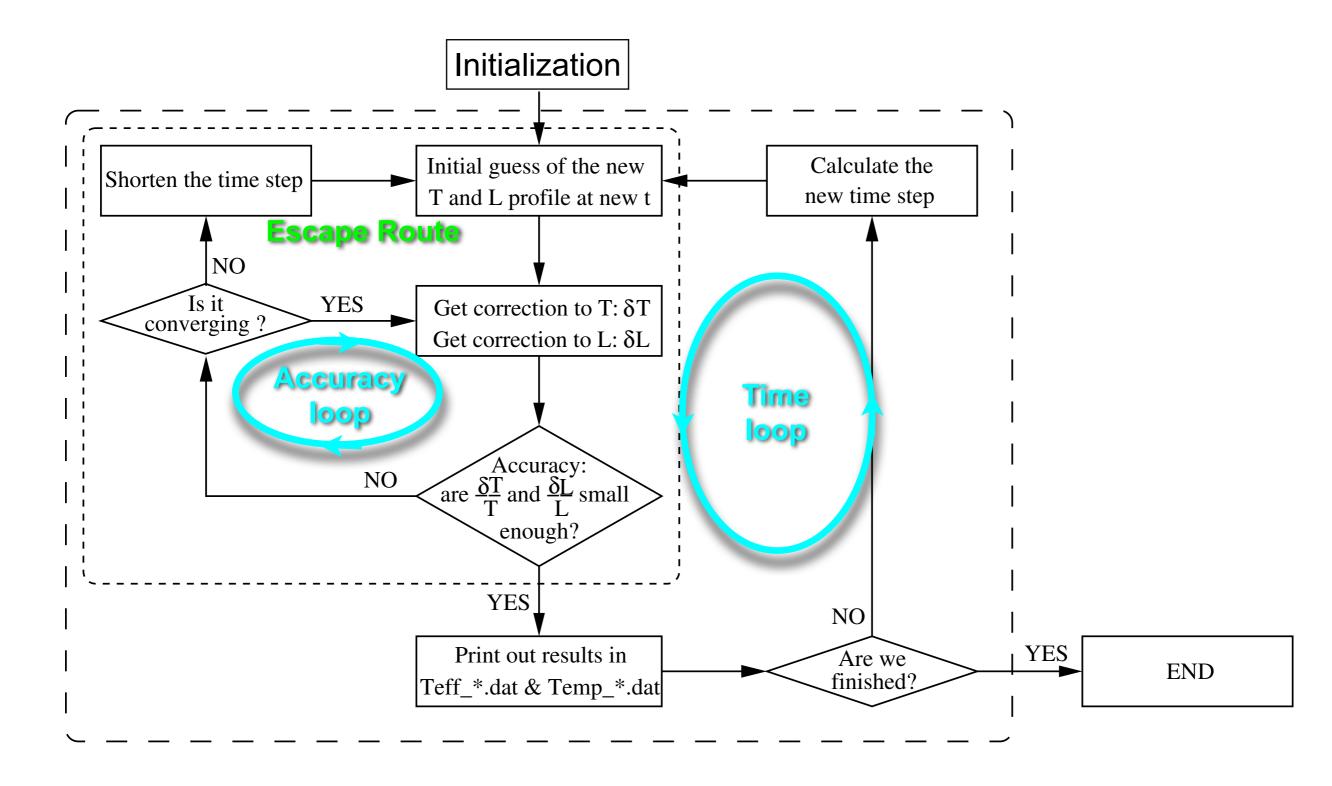
3) If finding the solutions required more than the desired number of iterations, scale_dt is also reduced.

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Flow diagram of NSCool (bigger)



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Up-date $\mathcal{T}\& \mathcal{L}$

Iterations have converged: ntemp(i) and nlum(i) are the solution \mathcal{T}_i and \mathcal{L}_i . They are copied to temp(i) and lum(i) so that they become the $\mathcal{T}_i^{\text{old}}$ and $\mathcal{L}_i^{\text{old}}$ at next time step.

[The variables "osomething" are so defined that, at next time step ,they will refer to two time steps back: they will be used to guess the initial profiles $\mathcal{T}_{i}^{(k=0)}$ and $\mathcal{L}_{i}^{(k=0)}$ by extrapolating.]

The following sections calculate a bunch of things for information purpose.

00	NSCool.f	0
C ********	*******	2
c ***** End of iterations		

<pre>do 171 i=1,imax,2 otemp(i)=temp(i) temp(i)=ntemp(i) orrho(i)=rrho(i) orad(i)=rad(i) obar(i)=bar(i) 171 continue</pre>		
<pre>do 172 i=2,imax-1,2 olum(i)=lum(i) lum(i)=nlum(i) orrho(i)=rrho(i) orad(i)=rad(i) obar(i)=bar(i)</pre>	2	
172 continue		1
-:** NSCool.f 74% (963,0)	0) (Fortran)	

● ○ ○ NSCool.f	C
C ++++++++++++++++++++++++++++++++++++	
c ++++++++++++++++++++++++++++++++++++	
c	
c Stuff below, till the next +++++ line is only informative and not	
c used in the calculations.	
-:** NSCool.f 77% (996,0) (Fortran)	
¢ ************************************	
c ***** Calculate the neutrino luminosity and heating: ************************************	
C ************************************	
-:** NSCool.f 79% (1038,0) (Fortran)	
c ***** CALCULATE THE INTEGRATED NEUTRINO LUMINOSITIES: ************************************	
c Note: lnu_tot, calculated from qnu(i), is the garanteed total	
c neutrino luminosity. The other ones are only informative.	
-:** NSCool.f 81% (1057,0) (Fortran)	
c ***** CALCULATE THE INTEGRATED SPECIFIC HEATS: ************************************	
c cv_tot_all, calculated from cv(i), is the garanteed total	
c specific heat. The other ones are only informative.	
-:** NSCool.f 82% (1078,0) (Fortran)	
с +	
k	
· ····································	
C ++++++++++++++++++++++++++++++++++++	
-:** NSCool.f 85% (1117,0) (Fortran)	



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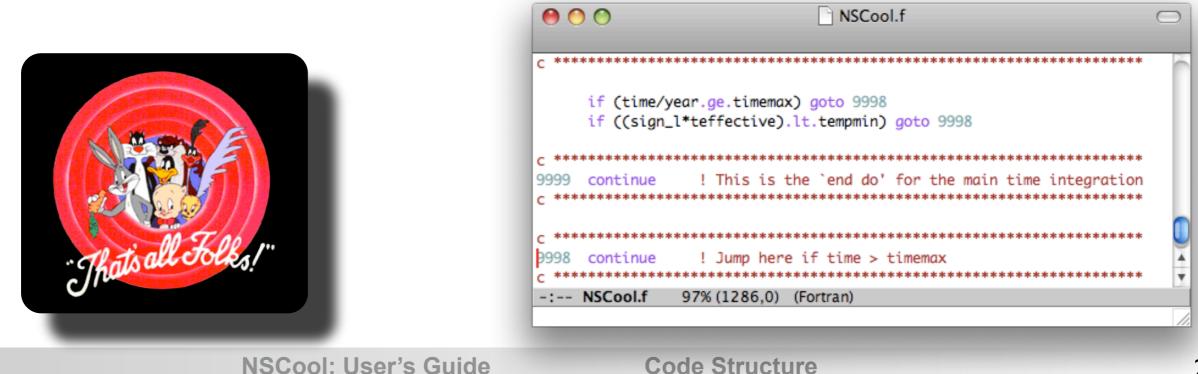


Print out results in the files
"Teff_*.dat" and "Temp_*.dat"
[all done in file NSCool_PRINT.inc.f]

Update the time variable

SCool.f	\bigcirc
c ************************************	ŕ
C ************************************	0
<pre>INCLUDE 'NSCool_PRINT.inc.f'</pre>	4
-:** NSCool.f 86% (1121,0) (Fortran)	
C ************************************	
<pre>time=time+dtime odtime=dtime dtime=min(scale_dt*dtime,dtlimit)</pre>	
-:** NSCool.f 91% (1197,0) (Fortran)	1
	1

Follow two sections to control dtime in case of accretion: more on this later !



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